APPENDIX OF PENDING CLAIMS

1. (Once Amended) A transducer for converting from electrical energy to mechanical energy, the transducer comprising:

at least two electrodes; and

a polymer arranged in a manner which causes a portion of the polymer to deflect in response to a change in electric field, wherein a portion of the polymer is elastically pre-strained by a factor in the range of about 1.5 times to 50 times the original area.

- 2. The transducer of claim 1 wherein the transducer has a maximum linear strain of at least about 50 percent in response to the change in electric field.
- 3. The transducer of claim 1 wherein the transducer has a maximum linear strain of at least about 100 percent in response to the change in electric field.
- 4. The transducer of claim 1 wherein the transducer has a maximum area strain of at least about 100 percent in response to the change in electric field.
- 5. The transducer of claim 1 wherein the pre-strain is applied to a first orthogonal direction at a pre-strain greater than pre-strain in a second orthogonal direction.
- 6. The transducer of claim 5 wherein the pre-strain applied to the first orthogonal direction is used to enhance deflection in the second orthogonal direction.
- 7. (Once Amended) The transducer of claim 6 wherein the polymer has a dielectric constant between about 2 and about 20.
- 8. The transducer of claim 1 wherein the polymer comprises one of a silicone rubber and an acrylic.
- 9. The transducer of claim 1 further comprising a barrier layer.

- 10. The transducer of claim 1 wherein the polymer comprises a textured surface.
- 11. The transducer of claim 1 wherein the polymer has a thickness between about 1 micrometer and 2 millimeters.
- 12. The transducer of claim 1 wherein the polymer is one of a commercially available silicone elastomer, polyurethane, PVDF copolymer or adhesive elastomer.
- 13. The transducer of claim 1 wherein the change in electric field is at most about 440 MegaVolts/meter.
- 14. The transducer of claim 1 wherein the polymer has a maximum actuation pressure between about 0.1 Pa and about 10 MPa.
- 15. The transducer of claim 1 wherein the polymer has an operational frequency less than about 100 kHz.
- 16. The transducer of claim 1 wherein the polymer has an elastic modulus below about 100 MPa.
- 17. The transducer of claim 1 wherein the portion of the polymer deflects out of the plane of the polymer in response to the change in electric field.
- 18. The transducer of claim 1 further comprising a stiff member attached to a portion of the polymer.
- 19. The transducer of claim 18 wherein the stiff member is included in a frame.
- 20. The transducer of claim 1 wherein one of the at least two electrodes is compliant.
- 21. The transducer of claim 1 further comprising a second polymer arranged in a manner which causes a portion of the second polymer to deflect in response to a second change in electric field and the second polymer is coupled to the first pre-strained polymer.
- 22. The transducer of claim 21 wherein the second polymer is mechanically coupled to the first polymer such that they have the same deflection.

- 23. The transducer of claim 1 wherein the transducer is included in an artificial muscle.
- 24. A transducer for converting electrical energy to mechanical energy, the transducer comprising:

at least two electrodes; and

a polymer arranged in a manner which causes a portion of the polymer to deflect in response to a change in electric field provided by the at least two electrodes, wherein the portion deflects with a maximum linear strain between about 50 percent and about 215 percent in response to the change in electric field.

- 25. The transducer of claim 24 wherein the polymer comprises one of a silicone rubber and an acrylic.
- 26. The transducer of claim 24 wherein the polymer is one of a commercially available silicone elastomer, polyurethane, PVDF copolymer or adhesive elastomer.
- 27-52. Withdrawn from Consideration.
- 53. (New) The transducer of claim 24 wherein the polymer has a dielectric constant between about 2 and about 20.
- 54. (New) The transducer of claim 24 wherein the polymer comprises one of a silicone rubber and an acrylic.
- 55. (New) The transducer of claim 24 wherein the polymer has a thickness between about 1 micrometer and 2 millimeters.

- 56. (New) The transducer of claim 24 wherein the polymer has an elastic modulus below about 100 MPa.
- 57. (New) The transducer of claim 24 wherein the portion of the polymer deflects out of the plane of the polymer in response to the change in electric field.
- 58. (New) The transducer of claim 24 further comprising a stiff member attached to a portion of the polymer.
- 59. (New) The transducer of claim 24 wherein the transducer is included in an artificial muscle.